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Robust Adaptive Control - G.C. Goodwin 2014-05-23

The workshop brought together international experts in the field of robust adaptive control to present recent developments in the area. These indicated that the theory of adaptive control is moving closer to applications and is beginning to give realistic guidelines useful in practical situations. The proceedings also focused on the value of such practical features as filtering, normalization, deadzones and unification of robust control and adaptation.

Aircraft Control and Simulation - Brian L. Stevens 2015-10-02

Get a complete understanding of aircraft control and simulation Aircraft Control and Simulation: Dynamics, Controls Design, and Autonomous Systems, Third Edition is a comprehensive guide to aircraft control and simulation. This updated text covers flight control systems, flight dynamics, aircraft modeling, and flight simulation from both classical design and modern perspectives, as well as two new chapters on the modeling, simulation, and adaptive control of unmanned aerial vehicles. With detailed examples, including relevant MATLAB calculations and FORTRAN codes, this approachable yet detailed reference also provides access to supplementary materials, including chapter problems and an instructor's solution manual. Aircraft control, as a subject area, combines an understanding of aerodynamics with knowledge of the physical systems of an aircraft. The ability to analyze the performance of an aircraft both in the real world and in computer-simulated flight is essential to maintaining proper control and function of the aircraft. Keeping up with the skills necessary to perform this analysis is critical for you to thrive in the aircraft control field. Explore a steadily progressing list of topics, including equations of motion and aerodynamics, classical controls, and more advanced control methods Consider detailed control design examples using computer

numerical tools and simulation examples Understand control design methods as they are applied to aircraft nonlinear math models Access updated content about unmanned aircraft (UAVs) Aircraft Control and Simulation: Dynamics, Controls Design, and Autonomous Systems, Third Edition is an essential reference for engineers and designers involved in the development of aircraft and aerospace systems and computer-based flight simulations, as well as upper-level undergraduate and graduate students studying mechanical and aerospace engineering.

Adaptive Backstepping Control of Uncertain Systems - Jing Zhou 2008-02-07

This book employs the powerful and popular adaptive backstepping control technology to design controllers for dynamic uncertain systems with non-smooth nonlinearities. Various cases including systems with time-varying parameters, multi-inputs and multi-outputs, backlash, dead-zone, hysteresis and saturation are considered in design and analysis. For multi-inputs and multi-outputs systems, both centralized and decentralized controls are addressed. This book not only presents recent research results including theoretical success and practical development such as the proof of system stability and the improvement of system tracking and transient performance, but also gives self-contained coverage of fundamentals on the backstepping approach illustrated with simple examples. Detail description of methodologies for the construction of adaptive laws, feedback control laws and associated Lyapunov functions is systematically provided in each case. Approaches used for the analysis of system stability and tracking and transient performances are elaborated. Two case studies are presented to show how the presented theories are applied.

Delay Compensation for Nonlinear, Adaptive, and PDE Systems - Miroslav Krstic 2010-01-23

Shedding light on new opportunities in predictor feedback, this book significantly broadens the set of techniques available to a mathematician or engineer working on delay systems. It is a collection of tools and techniques that make predictor feedback ideas applicable to nonlinear systems, systems modeled by PDEs, systems with highly uncertain or completely unknown input/output delays, and systems whose actuator or sensor dynamics are modeled by more general hyperbolic or parabolic PDEs, rather than by pure delay. Replete with examples, Delay Compensation for Nonlinear, Adaptive, and PDE Systems is an excellent reference guide for graduate students, researchers, and professionals in mathematics, systems control, as well as chemical, mechanical, electrical, computer, aerospace, and civil/structural engineering. Parts of the book may be used in graduate courses on general distributed parameter systems, linear delay systems, PDEs, nonlinear control, state estimator and observers, adaptive control, robust control, or linear time-varying systems.

Advances in Aerospace Guidance, Navigation and Control - Qiping Chu 2013-11-18

Following the successful 1st CEAS (Council of European Aerospace Societies) Specialist Conference on Guidance, Navigation and Control (CEAS EuroGNC) held in Munich, Germany in 2011, Delft University of Technology happily accepted the invitation of organizing the 2nd CEAS EuroGNC in Delft, The Netherlands in 2013. The goal of the conference is to promote new advances in aerospace GNC theory and technologies for enhancing safety, survivability, efficiency, performance, autonomy and intelligence of aerospace systems using on-board sensing, computing and systems. A great push for new developments in GNC are the ever higher safety and sustainability requirements in aviation. Impressive progress was made in new research fields such as sensor and actuator fault

detection and diagnosis, reconfigurable and fault tolerant flight control, online safe flight envelop prediction and protection, online global aerodynamic model identification, online global optimization and flight upset recovery. All of these challenges depend on new online solutions from on-board computing systems. Scientists and engineers in GNC have been developing model based, sensor based as well as knowledge based approaches aiming for highly robust, adaptive, nonlinear, intelligent and autonomous GNC systems. Although the papers presented at the conference and selected in this book could not possibly cover all of the present challenges in the GNC field, many of them have indeed been addressed and a wealth of new ideas, solutions and results were proposed and presented. For the 2nd CEAS Specialist Conference on Guidance, Navigation and Control the International Program Committee conducted a formal review process. Each paper was reviewed in compliance with good journal practice by at least two independent and anonymous reviewers. The papers published in this book were selected from the conference proceedings based on the results and recommendations from the reviewers.

Model Free Adaptive Control - Zhongsheng Hou 2013-09-24

Model Free Adaptive Control: Theory and Applications summarizes theory and applications of model-free adaptive control (MFAC). MFAC is a novel adaptive control method for the unknown discrete-time nonlinear systems with time-varying parameters and time-varying structure, and the design and analysis of MFAC merely depend on the measured input and output data of the controlled plant, which makes it more applicable for many practical plants. This book covers new concepts, including pseudo partial derivative, pseudo gradient, pseudo Jacobian matrix, and generalized Lipschitz conditions, etc.; dynamic linearization approaches for nonlinear systems, such as compact-form

dynamic linearization, partial-form dynamic linearization, and full-form dynamic linearization; a series of control system design methods, including MFAC prototype, model-free adaptive predictive control, model-free adaptive iterative learning control, and the corresponding stability analysis and typical applications in practice. In addition, some other important issues related to MFAC are also discussed. They are the MFAC for complex connected systems, the modularized controller designs between MFAC and other control methods, the robustness of MFAC, and the symmetric similarity for adaptive control system design. The book is written for researchers who are interested in control theory and control engineering, senior undergraduates and graduated students in engineering and applied sciences, as well as professional engineers in process control.

Robust and Adaptive Control - Eugene Lavretsky 2012-11-13

Robust and Adaptive Control shows the reader how to produce consistent and accurate controllers that operate in the presence of uncertainties and unforeseen events. Driven by aerospace applications the focus of the book is primarily on continuous-dynamical systems. The text is a three-part treatment, beginning with robust and optimal linear control methods and moving on to a self-contained presentation of the design and analysis of model reference adaptive control (MRAC) for nonlinear uncertain dynamical systems. Recent extensions and modifications to MRAC design are included, as are guidelines for combining robust optimal and MRAC controllers. Features of the text include: · case studies that demonstrate the benefits of robust and adaptive control for piloted, autonomous and experimental aerial platforms; · detailed background material for each chapter to motivate theoretical developments; · realistic examples and simulation data illustrating key features of the methods described; and ·

problem solutions for instructors and MATLAB® code provided electronically. The theoretical content and practical applications reported address real-life aerospace problems, being based on numerous transitions of control-theoretic results into operational systems and airborne vehicles that are drawn from the authors' extensive professional experience with The Boeing Company. The systems covered are challenging, often open-loop unstable, with uncertainties in their dynamics, and thus requiring both persistently reliable control and the ability to track commands either from a pilot or a guidance computer. Readers are assumed to have a basic understanding of root locus, Bode diagrams, and Nyquist plots, as well as linear algebra, ordinary differential equations, and the use of state-space methods in analysis and modeling of dynamical systems. Robust and Adaptive Control is intended to methodically teach senior undergraduate and graduate students how to construct stable and predictable control algorithms for realistic industrial applications. Practicing engineers and academic researchers will also find the book of great instructional value.

Robust Autonomous Guidance - Alberto Isidori 2012-12-06

From the reviews: "The book is an excellent combination of theory and real-world applications. Each application not only demonstrates the power of the theoretical results but also is important on its own behalf." IEEE Control Systems Magazine

Robust Control Design with MATLAB® - Da-Wei Gu 2006-03-30

Shows readers how to exploit the capabilities of the MATLAB® Robust Control and Control Systems Toolboxes to the fullest using practical robust control examples.

Advanced Control Systems - Theory and Applications - Yuriy P. Kondratenko 2021-07-08

Advanced Control Systems: Theory and Applications provides an overview of advanced

research lines in control systems as well as in design, development and implementation methodologies for perspective control systems and their components in different areas of industrial and special applications. It consists of extended versions of the selected papers presented at the XXV International Conference on Automatic Control “Automatics 2018” (September 18-19, 2018, Lviv, Ukraine) which is the main Ukrainian Control Conference organized by Ukrainian Association on Automatic Control (National member organization of IFAC) and Lviv National University “Lvivska Politechnica.” More than 100 papers were presented at the conference with topics including: mathematical problems of control, optimization and game theory; control and identification under uncertainty; automated control of technical, technological and biotechnical objects; controlling the aerospace craft, marine vessels and other moving objects; intelligent control and information processing; mechatronics and robotics; information measuring technologies in automation; automation and IT training of personnel; the Internet of things and the latest technologies. The book is divided into two main parts, the first concerning theory (7 chapters) and the second concerning applications (7 chapters) of advanced control systems. The first part “Advances in Theoretical Research on Automatic Control” consists of theoretical research results which deal with descriptor control impulsive delay systems, motion control in condition of conflict, inverse dynamic models, invariant relations in optimal control, robust adaptive control, bio-inspired algorithms, optimization of fuzzy control systems, and extremal routing problem with constraints and complicated cost functions. The second part “Advances in Control Systems Applications” is based on the chapters which consider different aspects of practical implementation of advanced control systems, in particular, special cases in determining the

spacecraft position and attitude using computer vision system, the spacecraft orientation by information from a system of stellar sensors, control synthesis of rotational and spatial spacecraft motion at approaching stage of docking, intelligent algorithms for the automation of complex biotechnical objects, an automatic control system for the slow pyrolysis of organic substances with variable composition, simulation complex of hierarchical systems based on the foresight and cognitive modelling, and advanced identification of impulse processes in cognitive maps. The chapters have been structured to provide an easy-to-follow introduction to the topics that are addressed, including the most relevant references, so that anyone interested in this field can get started in the area. This book may be useful for researchers and students who are interested in advanced control systems.

Control Systems - Jitendra R. Raol 2019-07-12

Control Systems: Classical, Modern, and AI-Based Approaches provides a broad and comprehensive study of the principles, mathematics, and applications for those studying basic control in mechanical, electrical, aerospace, and other engineering disciplines. The text builds a strong mathematical foundation of control theory of linear, nonlinear, optimal, model predictive, robust, digital, and adaptive control systems, and it addresses applications in several emerging areas, such as aircraft, electro-mechanical, and some nonengineering systems: DC motor control, steel beam thickness control, drum boiler, motional control system, chemical reactor, head-disk assembly, pitch control of an aircraft, yaw-damper control, helicopter control, and tidal power control. Decentralized control, game-theoretic control, and control of hybrid systems are discussed. Also, control systems based on artificial neural networks, fuzzy logic, and genetic algorithms, termed as AI-based systems are studied and analyzed with applications such

as auto-landing aircraft, industrial process control, active suspension system, fuzzy gain scheduling, PID control, and adaptive neuro control. Numerical coverage with MATLAB® is integrated, and numerous examples and exercises are included for each chapter. Associated MATLAB® code will be made available.

System Structure and Control 1992 - V. Strejc 2014-06-28

Provides a useful reference source on system structure and control. Covers, linear systems, nonlinear systems, robust control, implicit system, chaotic systems, singular and time-varying systems.

Smart Civil Structures - You-Lin Xu 2017-04-11

A smart civil structure integrates smart materials, sensors, actuators, signal processors, communication networks, power sources, diagonal strategies, control strategies, repair strategies, and life-cycle management strategies. It should function optimally and safely in its environment and maintain structural integrity during strong winds, severe earthquakes, and other extreme events. This book extends from the fundamentals to the state-of-the-art. It covers the elements of smart civil structures, their integration, and their functions. The elements consist of smart materials, sensors, control devices, signal processors, and communication networks. Integration refers to multi-scale modelling and model updating, multi-type sensor placement, control theory, and collective placement of control devices and sensors. And the functions include structural health monitoring, structural vibration control, structural self-repairing, and structural energy harvesting, with emphasis on their synthesis to form truly smart civil structures. It suits civil engineering students, professionals, and researchers with its blend of principles and practice.

Helicopter Flight Dynamics - Gareth D. Padfield 2018-09-07

The Book The behaviour of helicopters and tiltrotor aircraft is so complex that understanding the physical mechanisms at work in trim, stability and response, and thus the prediction of Flying Qualities, requires a framework of analytical and numerical modelling and simulation. Good Flying Qualities are vital for ensuring that mission performance is achievable with safety and, in the first and second editions of Helicopter Flight Dynamics, a comprehensive treatment of design criteria was presented, relating to both normal and degraded Flying Qualities. Fully embracing the consequences of Degraded Flying Qualities during the design phase will contribute positively to safety. In this third edition, two new Chapters are included. Chapter 9 takes the reader on a journey from the origins of the story of Flying Qualities, tracing key contributions to the developing maturity and to the current position. Chapter 10 provides a comprehensive treatment of the Flight Dynamics of tiltrotor aircraft; informed by research activities and the limited data on operational aircraft. Many of the unique behavioural characteristics of tiltrotors are revealed for the first time in this book. The accurate prediction and assessment of Flying Qualities draws on the modelling and simulation discipline on the one hand and testing practice on the other. Checking predictions in flight requires clearly defined mission tasks, derived from realistic performance requirements. High fidelity simulations also form the basis for the design of stability and control augmentation systems, essential for conferring Level 1 Flying Qualities. The integrated description of flight dynamic modelling, simulation and flying qualities of rotorcraft forms the subject of this book, which will be of interest to engineers practising and honing their skills in research laboratories, academia and manufacturing industries, test pilots and flight test engineers, and as a reference for graduate and postgraduate students in aerospace engineering.

Adaptive Control for Robotic Manipulators - Dan Zhang 2017-02-03

The robotic mechanism and its controller make a complete system. As the robotic mechanism is reconfigured, the control system has to be adapted accordingly. The need for the reconfiguration usually arises from the changing functional requirements. This book will focus on the adaptive control of robotic manipulators to address the changed conditions. The aim of the book is to summarise and introduce the state-of-the-art technologies in the field of adaptive control of robotic manipulators in order to improve the methodologies on the adaptive control of robotic manipulators. Advances made in the past decades are described in the book, including adaptive control theories and design, and application of adaptive control to robotic manipulators.

Aeroservoelasticity - Ashish Tewari 2015-03-24

This monograph presents the state of the art in aeroservoelastic (ASE) modeling and analysis and develops a systematic theoretical and computational framework for use by researchers and practicing engineers. It is the first book to focus on the mathematical modeling of structural dynamics, unsteady aerodynamics, and control systems to evolve a generic procedure to be applied for ASE synthesis. Existing robust, nonlinear, and adaptive control methodology is applied and extended to some interesting ASE problems, such as transonic flutter and buffet, post-stall buffet and maneuvers, and flapping flexible wing. The author derives a general aeroservoelastic plant via the finite-element structural dynamic model, unsteady aerodynamic models for various regimes in the frequency domain, and the associated state-space model by rational function approximations. For more advanced models, the full-potential, Euler, and Navier-Stokes methods for treating transonic and separated flows are also briefly addressed. Essential ASE controller design and analysis

techniques are introduced to the reader, and an introduction to robust control-law design methods of LQG/LTR and H2/H∞ synthesis is followed by a brief coverage of nonlinear control techniques of describing functions and Lyapunov functions. Practical and realistic aeroservoelastic application examples derived from actual experiments are included throughout. Aeroservoelasiticity fills an important gap in the aerospace engineering literature and will be a valuable guide for graduate students and advanced researchers in aerospace engineering, as well as professional engineers, technicians, and test pilots in the aircraft industry and laboratories.

Robotics and Mechatronics for Agriculture - Dan Zhang 2017-11-23

The aim of the book is to introduce the state-of-the-art technologies in the field of robotics, mechatronics and automation in agriculture in order to summarize and review the improvements in the methodologies in agricultural robotics. Advances made in the past decades are described, including robotics for agriculture, mechatronics for agriculture, kinematics, dynamics and control analysis of agricultural robotics, and a wide range of topics in the field of robotics, mechatronics and automation for agricultural applications.

High Performance Control - Teng-Tiow Tay 2012-12-06

The engineering objective of high performance control using the tools of optimal control theory, robust control theory, and adaptive control theory is more achiev able now than ever before, and the need has never been greater. Of course, when we use the term high peiformance control we are thinking of achieving this in the real world with all its complexity, uncertainty and variability. Since we do not expect to always achieve our desires, a more complete title for this book could be "Towards High Performance Control". To illustrate our task, consider as an example a disk drive tracking system for a

portable computer. The better the controller performance in the presence of eccen tricity uncertainties and external disturbances, such as vibrations when operated in a moving vehicle, the more tracks can be used on the disk and the more memory it has. Many systems today are control system limited and the quest is for high performance in the real world.

Algorithmic Foundations of Robotics XIV - Steven M. LaValle 2021-03-12

This proceedings book helps bring insights from this array of technical sub-topics together, as advanced robot algorithms draw on the combined expertise of many fields—including control theory, computational geometry and topology, geometrical and physical modeling, reasoning under uncertainty, probabilistic algorithms, game theory, and theoretical computer science. Intelligent robots and autonomous systems depend on algorithms that efficiently realize functionalities ranging from perception to decision making, from motion planning to control. The works collected in this SPAR book represent the state of the art in algorithmic robotics. They originate from papers accepted to the 14th International Workshop on the Algorithmic Foundations of Robotics (WAFR), traditionally a biannual, single-track meeting of leading researchers in the field of robotics. WAFR has always served as a premiere venue for the publication of some of robotics' most important, fundamental, and lasting algorithmic contributions, ensuring the rapid circulation of new ideas. Though an in-person meeting was planned for June 15–17, 2020, in Oulu, Finland, the event ended up being canceled owing to the infeasibility of international travel during the global COVID-19 crisis.

Cooperative Control of Multi-Agent Systems - Jianan Wang 2020-03-25

Cooperative Control of Multi-Agent Systems: An Optimal and Robust Perspective reports and encourages technology transfer in the field of

cooperative control of multi-agent systems. The book deals with UGVs, UAVs, UUVs and spacecraft, and more. It presents an extended exposition of the authors' recent work on all aspects of multi-agent technology. Modelling and cooperative control of multi-agent systems are topics of great interest, across both academia (research and education) and industry (for real applications and end-users). Graduate students and researchers from a wide spectrum of specialties in electrical, mechanical or aerospace engineering fields will use this book as a key resource. Helps shape the reader's understanding of optimal and robust cooperative control design techniques for multi-agent systems Presents new theoretical control challenges and investigates unresolved/open problems Explores future research trends in multi-agent systems Offers a certain amount of analytical mathematics, practical numerical procedures, and actual implementations of some proposed approaches

Flight Dynamics Principles - Michael V. Cook 2012-10-03

The study of flight dynamics requires a thorough understanding of the theory of the stability and control of aircraft, an appreciation of flight control systems and a grounding in the theory of automatic control. Flight Dynamics Principles is a student focused text and provides easy access to all three topics in an integrated modern systems context. Written for those coming to the subject for the first time, the book provides a secure foundation from which to move on to more advanced topics such as, non-linear flight dynamics, flight simulation, handling qualities and advanced flight control. New to this edition: Additional examples to illustrate the application of computational procedures using tools such as MATLAB®, MathCad® and Program CC® Improved compatibility with, and more expansive coverage of the North American notational style Expanded coverage of lateral-directional static stability, manoeuvrability,

command augmentation and flight in turbulence An additional coursework study on flight control design for an unmanned air vehicle (UAV)

Robust and Adaptive Control - Eugene Lavretsky 2012-11-13

Robust and Adaptive Control shows the reader how to produce consistent and accurate controllers that operate in the presence of uncertainties and unforeseen events. Driven by aerospace applications the focus of the book is primarily on continuous-dynamical systems. The text is a three-part treatment, beginning with robust and optimal linear control methods and moving on to a self-contained presentation of the design and analysis of model reference adaptive control (MRAC) for nonlinear uncertain dynamical systems. Recent extensions and modifications to MRAC design are included, as are guidelines for combining robust optimal and MRAC controllers. Features of the text include: · case studies that demonstrate the benefits of robust and adaptive control for piloted, autonomous and experimental aerial platforms; · detailed background material for each chapter to motivate theoretical developments; · realistic examples and simulation data illustrating key features of the methods described; and · problem solutions for instructors and MATLAB® code provided electronically. The theoretical content and practical applications reported address real-life aerospace problems, being based on numerous transitions of control-theoretic results into operational systems and airborne vehicles that are drawn from the authors' extensive professional experience with The Boeing Company. The systems covered are challenging, often open-loop unstable, with uncertainties in their dynamics, and thus requiring both persistently reliable control and the ability to track commands either from a pilot or a guidance computer. Readers are assumed to have a basic understanding of root locus, Bode diagrams, and Nyquist plots, as well as linear algebra, ordinary differential equations, and the

use of state-space methods in analysis and modeling of dynamical systems. Robust and Adaptive Control is intended to methodically teach senior undergraduate and graduate students how to construct stable and predictable control algorithms for realistic industrial applications. Practicing engineers and academic researchers will also find the book of great instructional value.

Adaptive Robust Control Systems - Anh Tuan Le 2018-03-07

This book focuses on the applications of robust and adaptive control approaches to practical systems. The proposed control systems hold two important features: (1) The system is robust with the variation in plant parameters and disturbances (2) The system adapts to parametric uncertainties even in the unknown plant structure by self-training and self-estimating the unknown factors. The various kinds of robust adaptive controls represented in this book are composed of sliding mode control, model-reference adaptive control, gain-scheduling, H-infinity, model-predictive control, fuzzy logic, neural networks, machine learning, and so on. The control objects are very abundant, from cranes, aircrafts, and wind turbines to automobile, medical and sport machines, combustion engines, and electrical machines.

Robust Adaptive Control - Petros Ioannou 2013-09-26

Presented in a tutorial style, this comprehensive treatment unifies, simplifies, and explains most of the techniques for designing and analyzing adaptive control systems. Numerous examples clarify procedures and methods. 1995 edition.

Hamilton-Jacobi-Bellman Equations - Dante Kalise 2018-08-06

Optimal feedback control arises in different areas such as aerospace engineering, chemical processing, resource economics, etc. In this context, the application of dynamic programming techniques leads to the solution of

fully nonlinear Hamilton-Jacobi-Bellman equations. This book presents the state of the art in the numerical approximation of Hamilton-Jacobi-Bellman equations, including post-processing of Galerkin methods, high-order methods, boundary treatment in semi-Lagrangian schemes, reduced basis methods, comparison principles for viscosity solutions, max-plus methods, and the numerical approximation of Monge-Ampère equations. This book also features applications in the simulation of adaptive controllers and the control of nonlinear delay differential equations. Contents From a monotone probabilistic scheme to a probabilistic max-plus algorithm for solving Hamilton–Jacobi–Bellman equations Improving policies for Hamilton–Jacobi–Bellman equations by postprocessing Viability approach to simulation of an adaptive controller Galerkin approximations for the optimal control of nonlinear delay differential equations Efficient higher order time discretization schemes for Hamilton–Jacobi–Bellman equations based on diagonally implicit symplectic Runge–Kutta methods Numerical solution of the simple Monge–Ampere equation with nonconvex Dirichlet data on nonconvex domains On the notion of boundary conditions in comparison principles for viscosity solutions Boundary mesh refinement for semi-Lagrangian schemes A reduced basis method for the Hamilton–Jacobi–Bellman equation within the European Union Emission Trading Scheme

Adaptive Control of Systems with Actuator Failures - Gang Tao 2013-06-29

This book shows readers new ways to compensate for disturbances in control systems prolonging the intervals between time-consuming and/or expensive fault diagnosis procedures, keeping them up to date in the increasingly important field of adaptive control.

L1 Adaptive Control Theory - Naira Hovakimyan 2010-09-30

Contains results not yet published in technical

journals and conference proceedings.

Adaptive Critic Control with Robust Stabilization for Uncertain Nonlinear Systems - Ding Wang 2018-08-10

This book reports on the latest advances in adaptive critic control with robust stabilization for uncertain nonlinear systems. Covering the core theory, novel methods, and a number of typical industrial applications related to the robust adaptive critic control field, it develops a comprehensive framework of robust adaptive strategies, including theoretical analysis, algorithm design, simulation verification, and experimental results. As such, it is of interest to university researchers, graduate students, and engineers in the fields of automation, computer science, and electrical engineering wishing to learn about the fundamental principles, methods, algorithms, and applications in the field of robust adaptive critic control. In addition, it promotes the development of robust adaptive critic control approaches, and the construction of higher-level intelligent systems.

Automatic Control in Aerospace 2004 - Alexander Nebylov 2005-10-03

Applications of Robust Control to Nonlinear Systems - Richard Dean Colgren 2004

Adaptive Control Tutorial - Petros Ioannou 2006-01-01

Designed to meet the needs of a wide audience without sacrificing mathematical depth and rigor, Adaptive Control Tutorial presents the design, analysis, and application of a wide variety of algorithms that can be used to manage dynamical systems with unknown parameters. Its tutorial-style presentation of the fundamental techniques and algorithms in adaptive control make it suitable as a textbook. Adaptive Control Tutorial is designed to serve the needs of three distinct groups of readers: engineers and students interested in learning how to design, simulate, and implement parameter estimators

and adaptive control schemes without having to fully understand the analytical and technical proofs; graduate students who, in addition to attaining the aforementioned objectives, also want to understand the analysis of simple schemes and get an idea of the steps involved in more complex proofs; and advanced students and researchers who want to study and understand the details of long and technical proofs with an eye toward pursuing research in adaptive control or related topics. The authors achieve these multiple objectives by enriching the book with examples demonstrating the design procedures and basic analysis steps and by detailing their proofs in both an appendix and electronically available supplementary material; online examples are also available. A solution manual for instructors can be obtained by contacting SIAM or the authors. Preface; Acknowledgements; List of Acronyms; Chapter 1: Introduction; Chapter 2: Parametric Models; Chapter 3: Parameter Identification: Continuous Time; Chapter 4: Parameter Identification: Discrete Time; Chapter 5: Continuous-Time Model Reference Adaptive Control; Chapter 6: Continuous-Time Adaptive Pole Placement Control; Chapter 7: Adaptive Control for Discrete-Time Systems; Chapter 8: Adaptive Control of Nonlinear Systems; Appendix; Bibliography; Index

Stable Adaptive Systems - Kumpati S. Narendra 2012-07-12

This graduate-level text offers a thorough understanding of the global stability properties essential to designing adaptive systems. Its self-contained, unified presentation includes detailed case studies and numerous problems. 1989 edition.

Optimal Control - Michael Athans 2013-04-26

Geared toward advanced undergraduate and graduate engineering students, this text introduces the theory and applications of optimal control. It serves as a bridge to the technical literature, enabling students to evaluate the

implications of theoretical control work, and to judge the merits of papers on the subject. Rather than presenting an exhaustive treatise, Optimal Control offers a detailed introduction that fosters careful thinking and disciplined intuition. It develops the basic mathematical background, with a coherent formulation of the control problem and discussions of the necessary conditions for optimality based on the maximum principle of Pontryagin. In-depth examinations cover applications of the theory to minimum time, minimum fuel, and to quadratic criteria problems. The structure, properties, and engineering realizations of several optimal feedback control systems also receive attention. Special features include numerous specific problems, carried through to engineering realization in block diagram form. The text treats almost all current examples of control problems that permit analytic solutions, and its unified approach makes frequent use of geometric ideas to encourage students' intuition.

Flight Dynamics and Control of Aero and Space Vehicles - Rama K. Yedavalli 2020-02-25 Flight Vehicle Dynamics and Control Rama K. Yedavalli, The Ohio State University, USA A comprehensive textbook which presents flight vehicle dynamics and control in a unified framework Flight Vehicle Dynamics and Control presents the dynamics and control of various flight vehicles, including aircraft, spacecraft, helicopter, missiles, etc, in a unified framework. It covers the fundamental topics in the dynamics and control of these flight vehicles, highlighting shared points as well as differences in dynamics and control issues, making use of the ‘systems level’ viewpoint. The book begins with the derivation of the equations of motion for a general rigid body and then delineates the differences between the dynamics of various flight vehicles in a fundamental way. It then focuses on the dynamic equations with application to these various flight vehicles, concentrating more on aircraft and spacecraft

cases. Then the control systems analysis and design is carried out both from transfer function, classical control, as well as modern, state space control points of view. Illustrative examples of application to atmospheric and space vehicles are presented, emphasizing the 'systems level' viewpoint of control design. Key features: Provides a comprehensive treatment of dynamics and control of various flight vehicles in a single volume. Contains worked out examples (including MATLAB examples) and end of chapter homework problems. Suitable as a single textbook for a sequence of undergraduate courses on flight vehicle dynamics and control. Accompanied by a website that includes additional problems and a solutions manual. The book is essential reading for undergraduate students in mechanical and aerospace engineering, engineers working on flight vehicle control, and researchers from other engineering backgrounds working on related topics.

Techniques for Adaptive Control - Vance VanDoren 2002-10-31

Techniques for Adaptive Control compiles chapters from a team of expert contributors that allow readers to gain a perspective into a number of different approaches to adaptive control. In order to do this, each contributor provides an overview of a particular product, how it works, and reasons why a user would want it as well as an in depth explanation of their particular method. This is one of the latest technologies to emerge in the instrumentation and control field. These latest control methodologies offer a means to revolutionize plant and process efficiency, response time and profitability by allowing a process to be regulated by a form of rule-based AI, without human intervention. Rather than the common academic-based approach that books on this subject generally take, the contributions here outline practical applications of adaptive control technology allowing for a real look inside the industry and the new technologies available. *

Written by a team of contributors from the industry's best-known product manufacturers and software developers * Provides real insight into new technologies available in the industry * Outlines practical applications of adaptive control technology

Fault-tolerant Flight Control and Guidance Systems - Guillaume J. J. Ducard 2009-05-14

This book offers a complete overview of fault-tolerant flight control techniques. Discussion covers the necessary equations for the modeling of small UAVs, a complete system based on extended Kalman filters, and a nonlinear flight control and guidance system.

Neural Network Modeling and Identification of Dynamical Systems - Yuri Tiumentsev 2019-05-17

Neural Network Modeling and Identification of Dynamical Systems presents a new approach on how to obtain the adaptive neural network models for complex systems that are typically found in real-world applications. The book introduces the theoretical knowledge available for the modeled system into the purely empirical black box model, thereby converting the model to the gray box category. This approach significantly reduces the dimension of the resulting model and the required size of the training set. This book offers solutions for identifying controlled dynamical systems, as well as identifying characteristics of such systems, in particular, the aerodynamic characteristics of aircraft. Covers both types of dynamic neural networks (black box and gray box) including their structure, synthesis and training Offers application examples of dynamic neural network technologies, primarily related to aircraft Provides an overview of recent achievements and future needs in this area

Applied Digital Control - J. R. Leigh 2006-06-23

An essential core text, this volume develops theoretical foundations and explains how control systems work in real industrial situations. Several case histories assist students in

visualizing applications. 1992 edition.

Applications of Neural Networks in High Assurance Systems - Johann M.Ph. Schumann 2010-03-10

"Applications of Neural Networks in High Assurance Systems" is the first book directly addressing a key part of neural network technology: methods used to pass the tough verification and validation (V&V) standards required in many safety-critical applications. The book presents what kinds of evaluation methods have been developed across many sectors, and how to pass the tests. A new adaptive structure of V&V is developed in this book, different from the simple six sigma methods usually used for large-scale systems and different from the theorem-based approach used for simplified component subsystems.

Model-Reference Adaptive Control - Nhan T. Nguyen 2018-03-01

This textbook provides readers with a good working knowledge of adaptive control theory through applications. It is intended for students beginning masters or doctoral courses, and control practitioners wishing to get up to speed in the subject expeditiously. Readers are taught a wide variety of adaptive control techniques starting with simple methods and extending step-by-step to more complex ones. Stability proofs are provided for all adaptive control techniques without obfuscating reader understanding with excessive mathematics. The book begins with standard model-reference adaptive control (MRAC) for first-order, second-order, and multi-input, multi-output systems. Treatment of least-squares parameter estimation and its extension to MRAC follow, helping readers to gain a different perspective on MRAC. Function approximation with orthogonal polynomials and neural networks, and MRAC using neural networks are also covered. Robustness issues connected with MRAC are discussed, helping the student to appreciate potential pitfalls of the technique. This

appreciation is encouraged by drawing parallels between various aspects of robustness and linear time-invariant systems wherever relevant. Following on from the robustness problems is material covering robust adaptive control including standard methods and detailed exposition of recent advances, in particular, the author's work on optimal control modification. Interesting properties of the new method are illustrated in the design of adaptive systems to meet stability margins. This method has been successfully flight-tested on research aircraft, one of various flight-control applications detailed towards the end of the book along with a hybrid adaptive flight control architecture that combines direct MRAC with least-squares indirect adaptive control. In addition to the applications, understanding is encouraged by the use of end-of-chapter exercises and associated MATLAB® files. Readers will need no more than the standard mathematics for basic control theory such as differential equations and matrix algebra; the book covers the foundations of MRAC and the necessary mathematical preliminaries.